

## Adv. Course in Programming Languages

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How to *stage* programs, precisely

- ▶ Type system of programming languages
- ▶ Type inference
- ▶ Type inference for staging (based on examples)

## Type System

```
let f x y z = if x then y + 1 else z * 3
==>
f : bool -> int -> int -> int
```

This type means

- ▶ x has type `bool`
- ▶ y has type `int`
- ▶ z has type `int`
- ▶ then, the return type of f is `int`

## Benefit of Types

Basic benefits

- ▶ Avoiding illegal instructions (e.g. `10 + "abc"`), “well-typed programs don't go wrong”.
- ▶ Lightweight documentation
- ▶ Efficiency (i.e. hint for compiler)
- ▶ Abstraction (interface vs implementation)

Advanced benefits

- ▶ Types can include more **static** information
- ▶ E.g. Static/Dynamic (staging), Invariant (verification), Security etc.

## Types for functional programming languages

```
let foo x = x+1 : int->int
```

```
let goo x y = x+y : int->int->int
```

```
let hoo x y = if x then y else y + 1
              : bool->int->int
```

## Type inference rules

$e = \text{if } e_1 \text{ then } e_2 \text{ else } e_3$

- ▶ type of  $e_1$  must be `bool`
- ▶ type of  $e_2$  can be arbitrary type ( $\alpha$ )
- ▶ type of  $e_3$  must be  $\alpha$
- ▶ type of  $e$  must be  $\alpha$

$e = x$

- ▶ type of  $x$  can be arbitrary type ( $\alpha$ )
- ▶ type of  $e$  must be  $\alpha$
- ▶ (and all occurrences of  $x$  must have the same type)

## Type inference rules

$e = 13$

- ▶ type of  $e$  must be `int`

$e = e_1 + e_2$

- ▶ type of  $e_1$  must be `int`
- ▶ type of  $e_2$  must be `int`
- ▶ type of  $e$  must be `int`

## Example of type inference

```
let rec power n x =
  if n=0 then 1
  else x * (power (n-1) x)
```

- ▶ let  $\alpha$  be type of  $n$
- ▶ let  $\beta$  be type of  $x$
- ▶ let  $\gamma$  be return type of `power`
- ▶ `n=0` has type `bool`,  $\alpha$  must be `int`
- ▶ `1` has type `int`, so  $\gamma$  is `int`
- ▶ `n-1` has type `int`
- ▶ `(power (n-1) x)` has type  $\gamma$ ,
- ▶ `x*(power (n-1) x)` has type `int` and  $\beta$  is `int`
- ▶ and everything else is OK

Hence, `power` has type `int->int->int`.

## Types for staging (naive version)

### Type S

- ▶ means type for static values (will be computed and erased)
- ▶ e.g. the parameter  $n$  of power has type S

### Type D

- ▶ means type for dynamic values (will become code)
- ▶ e.g. the parameter  $x$  of power has type D
- ▶ e.g. the return type of power is D

### Type $t1 \rightarrow t2$

- ▶ means function type from  $t1$  to  $t2$ .
- ▶ e.g. power is expected to have type  $S \rightarrow D \rightarrow D$

No types such as `int`, `bool`→`bool` etc.

## Notes on Types for Staging

Type D and type  $D \rightarrow D$  differ:

A MetaOCaml expression of Type D

```
<fun x -> x * 3>
```

A MetaOCaml expression of Type  $D \rightarrow D$

```
fun x -> < ~x * 3 >
```

A MetaOCaml expression of Type  $S \rightarrow D$

```
fun x -> if x then <3> else <5>
```

## Typing rules for staging

$e = e1 + e2$

- ▶ type of  $e1$ ,  $e2$ , and  $e$  are S, or
- ▶ type of  $e1$ ,  $e2$ , and  $e$  are D

$e = \text{if } e1 \text{ then } e2 \text{ else } e3$

- ▶ type of  $e1$  must be S or D, and
- ▶ type of  $e2, e3, e$  must be the same
- ▶ if type of  $e1$  is D, so is  $e$

## Typing rules for staging

$e = e1 \ e2$  (function call)

- ▶ type of  $e1$ ,  $e2$ ,  $e$  are D, or
- ▶ type of  $e1$  is  $\alpha \rightarrow \beta$ , where  $\alpha$  is type of  $e2$  and  $\beta$  is type of  $e$

$e = c$  (constant)

- ▶ type of  $e$  is S or D

## Example (1)

Power function:

```
let rec power n x =
  if n=0 then 1
  else x * (power (n-1) x)
```

Suppose  $n : S$  and  $x : D$ , return type is  $D$ .

- ▶  $\text{power} : S \rightarrow D \rightarrow D$
- ▶  $(n=0) : S$  and  $(n-1) : S$
- ▶  $1 : D$  or  $1 : S$
- ▶  $(\text{power } (n-1) \ x) : D$
- ▶  $x * (\text{power } (n-1) \ x) : D$ , hence then-part also has type  $D$ .
- ▶  $\text{if } \dots \text{then } \dots \text{else } \dots : D$  (the same as the return type)
- ▶ Ok!

## Refined system

Static values can be **lifted** to dynamic values.

```
lift 5
==> <5>
```

```
lift 5 : int code
lift   : int -> int code, or S -> D
```

When we stage a program we are allowed to insert lift at **any place**.

## Example (2)

Gib function:

```
let rec gib n x y =
  if n=0 then (x,y)
  else
    let (x1,y1)=gib (n-1) x y in
      (y1, x1+y1)
```

Suppose  $n : S$ ,  $x : S$ ,  $y : D$  and return type is unknown ( $\alpha$ ).

- ▶  $\text{gib} : S \rightarrow S \rightarrow D \rightarrow \alpha$ .
- ▶  $(n=0) : D$  or  $(n=0) : S$ .
- ▶  $(x,y) : S * D$  and  $\alpha = S * D$ .
- ▶  $(\text{gib } (n-1) \ x \ y) : S * D$ .
- ▶  $x1 : S$  and  $y1 : D$ .
- ▶  $(x1+y1)$  is NOT typable

## Example (2, again)

Gib function:

```
let rec gib n x y =
  if n=0 then (x,y)
  else
    let (x1,y1)=gib (n-1) x y in
      (y1, x1+y1)
```

Suppose  $n : S$ ,  $x : S$ ,  $y : D$  and return type is unknown ( $\alpha$ ).

- ▶  $\text{gib} : S \rightarrow S \rightarrow D \rightarrow \alpha$ .
- ▶  $(x,y) : S * D$  and  $\alpha = S * D$ .
- ▶  $(\text{gib } (n-1) \ x \ y) : S * D$ , and  $x1 : S$  and  $y1 : D$ .
- ▶  $(\text{lift}(x1)+y1) : D$ .
- ▶  $(x,y)$  in then-branch should be  $(\text{lift}(x),y)$  of type  $D * D$ .
- ▶ Ok! gib has type  $S \rightarrow S \rightarrow D \rightarrow (D * D)$ .

## Exercise: Infer the types

(1) Assume  $x : D$ ,  $y : S$ , and return type is  $D$ .

```
let rec goo x y =  
  if x > 100 then x - y  
  else goo (goo (x+11) y) y
```

(2) Assume  $a, b, c$  have type  $S$  and  $d$  and  $e$  have type  $D$ . return type is  $D$ .

```
let rec foo a b c d e =  
  if a > 0 then  
    foo (a+b) (b+c) (c+d) (d-e) (e*a)  
  else  
    foo 3 5 (foo b c d e a) 7 9
```

## Summary

Type system and type inference:

- ▶ Key component in modern programming languages (C, C++, ML family, Haskell, Java, Scala, etc.)
- ▶ Important tool for program analysis and verification; we can represent various **static information**, including binding time (static/dynamic), invariant, security level, by types.
- ▶ A very simple type system help stage programs.